

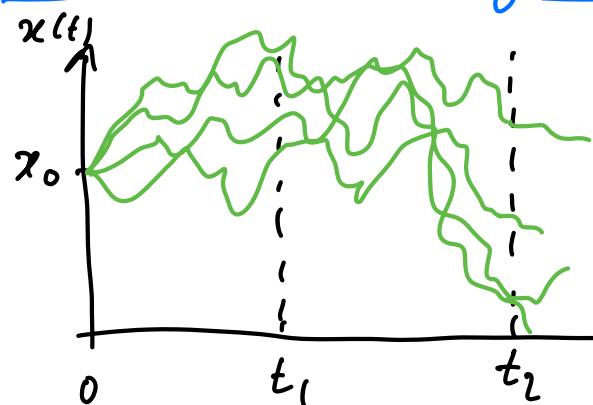
Chapter 3: The Fokker-Planck equation

①

Reference: Rishen, "The Fokker-Planck equation", Springer

Take $x(t)$ such that $x(0)=x_0$ & $\dot{x}(t) = F(x(t)) + \xi(t)$ (1), where ξ is a GWN s.t. $\langle \xi(t) \rangle = 0$, $\langle \xi(t) \xi(t') \rangle = 2D \delta(t-t')$

Consider several realizations of $x(t)$

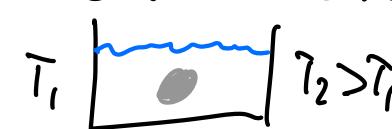


We denote by $P(x(t)=\bar{x}, t|x_0, 0)$ the probability that the process $x(t)$ reaches the position \bar{x} at time t , given that it was at x_0 at time 0.

More concisely, we write $P(\bar{x}, t|x_0, 0)$ and stress that \bar{x} & x_0 are numbers while $x(t)$ is a stochastic process.

Clearly $P(\bar{x}, t_1|x_0, 0) \neq P(\bar{x}, t_2|x_0, 0) \Rightarrow$ how does $P(\bar{x}, t|x_0, 0)$ evolves in time?

1) The Fokker-Planck Equation

In Eq (1), the statistics of $\xi(t)$ do not depend on $x(t)$. This is called an additive noise. Instead we can consider a case where, say, the temperature is inhomogeneous T_1  $T_2 > T_1$,

then $T(x)$ & the Langevin equation is of the type

$$\dot{x} = F(x) + \sqrt{2D(x)} \xi(t) \quad (2)$$

$$\text{with } \langle \xi \rangle = 0 \text{ & } \langle \xi(t) \xi(t') \rangle = \delta(t-t')$$

This is called a *multiplicative noise*. Itô formula can be extended to this case, which requires the time discretization of Eq (2) to be

$$x(t+\delta t) = x(t) + F(x(t))\delta t + \sqrt{2D(x(t))} \int_t^{t+\delta t} \xi(s) ds$$

Let us derive the evolution of $P(x, t | x_0, 0)$ in this more general case

Trick: $P(x, t | x_0, 0) = \int dg P(g, t | x_0, 0) \delta(x-g) = \langle \delta(x-g(t)) \rangle$

dummy integration variable number
number stochastic process P

$\langle \delta(g) \rangle = \int dg P(g, t | x_0, 0)$ $\langle \delta(g) \rangle$ is an average over the realization of the process $g(t)$.

Then we find

$$\begin{aligned}
 \frac{dP(x, t | x_0, 0)}{dt} &= \left\langle \frac{d}{dt} \delta(x-g(t)) \right\rangle_g \\
 &\stackrel{\text{If } \delta}{=} \left\langle \left[\partial_g \delta(x-g) \right] \dot{g} + \frac{1}{2} \langle \delta(g) \partial_g^2 \delta(x-g) \rangle_g \right\rangle \quad \text{where } \partial_g f \equiv \frac{df}{dg} \\
 &= \left\langle F(g) \partial_g \delta(x-g) \right\rangle + \underbrace{\left\langle \xi(t) \sqrt{2D(g(t))} \partial_g \delta(x-g(t)) \right\rangle}_{\stackrel{\text{If } \xi}{=} \langle \xi(t) \rangle \langle \sqrt{2D(g(t))} \partial_g \delta(x-g(t)) \rangle} + \left\langle D(g) \partial_g^2 \delta(x-g) \right\rangle
 \end{aligned}$$

Using that $\langle \delta(x) \rangle = \int dx \delta(x) P(x)$, we get

$$\frac{d}{dt} P(x, t | x_0, 0) = \int dg P(g, t | x_0, 0) \left[F(g) \partial_g \delta(x-g) + D(g) \partial_g^2 \delta(x-g) \right]$$

$$\stackrel{IBP}{=} \int dy \delta(x-y) \left\{ -\frac{\partial}{\partial y} \left[F(y) P(y, t|x_0, 0) \right] + \frac{\partial^2}{\partial y^2} \left[D(y) P(y, t|x_0, 0) \right] \right\} + \text{boundary terms}$$
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(3)

Boundary terms:

Case 1: periodic boundary condition $\left[\dots \right]_{\text{boundary 1}}^{\text{boundary 2}} = 0$

Case 2: closed box, $x \in [x_1, x_2]$, then $P(x < x_1 | x_0, 0) = P(x > x_2 | x_0, 0) = 0$

$$\Rightarrow \left[\dots \right]_{\text{boundary 1}}^{\text{boundary 2}} = 0$$

Case 3: infinite system. $\int dx P(x, t|x_0, 0) = 1 \Rightarrow P(x \rightarrow \infty, t|x_0, 0) = 0$

$$\Rightarrow \left[\dots \right]_{\text{boundary 1}}^{\text{boundary 2}} = 0$$

\Rightarrow In all standard cases, the boundary terms vanish.

Thus, in (3), $\int dy \delta(x-y) H(y) = H(x)$ so that

$$\frac{d}{dt} P(x, t|x_0, 0) = \frac{\partial}{\partial x} \left[-F(x) + \frac{\partial}{\partial x} D(x) \right] P(x, t|x_0, 0) \quad (4)$$

where $\frac{\partial}{\partial x}$ is an operator that acts on everything to its right.

This is the celebrated **Fokker-Planck equation**.

⚠ Be careful with the position of $D(x)$ that does not commute with $\frac{\partial}{\partial x}$.

Mathematical a parte

Let us follow a slightly more mathematical route to the FPE.

Let $f: \mathbb{R} \rightarrow \mathbb{R}$ be a C^2 function. By definition $\langle f(x_{t+1}) \rangle = \int dx f(x) P(x, t|x_0, 0)$

Thus
$$\frac{d}{dt} \langle f(x_{t+1}) \rangle = \int dx f(x) \frac{\partial P(x, t|x_0, 0)}{\partial t} \quad (1)$$

Itô formula also tells us that $\frac{d}{dt} f(x_{t+1}) = f'(x_{t+1}) \sigma + D f''(x_{t+1})$

Taking the average,

$$\begin{aligned} \frac{d}{dt} \langle f(x_{t+1}) \rangle &= \langle f'(x_{t+1}) \cdot F(x_{t+1}) \rangle + \underbrace{\langle f'(x_{t+1}) \xi(t) \rangle}_{\text{If } \langle f' \rangle \langle \xi \rangle D = 0} + D \langle f''(x_{t+1}) \rangle \\ &= \int dx \left[\frac{\partial f}{\partial x} \cdot F(x) P(x, t|x_0, 0) + D \frac{\partial^2 f}{\partial x^2} P(x, t|x_0, 0) \right] \\ &= \left[f(x) F(x) P(x, t|x_0, 0) + D f(x) P(x, t|x_0, 0) \right]_{\substack{\text{boundary 2} \\ \text{as before}}}^{\text{boundary 1}} \\ &\quad - \int dx \left\{ f(x) \frac{\partial}{\partial x} \left[F(x) P(x, t|x_0, 0) \right] + \frac{\partial f}{\partial x} \cdot \frac{\partial}{\partial x} \left[D P(x, t|x_0, 0) \right] \right\} \\ &= \int dx f(x) \left\{ \frac{\partial^2}{\partial x^2} \left[D P(x, t|x_0, 0) \right] - \frac{\partial}{\partial x} \left[F(x) P(x, t|x_0, 0) \right] \right\} \end{aligned}$$

① & ② hold for any function f so that

$$\frac{\partial P(x, t|x_0, 0)}{\partial t} = \frac{\partial}{\partial x} \left[\frac{\partial}{\partial x} (D - F(x)) \right] P(x, t|x_0, 0)$$

Intuition:

① $F=0$; $\dot{x} = \sqrt{2D} \zeta \Leftrightarrow$ random walk $\Rightarrow \frac{dP}{dt} = D \Delta P$ which is the diffusion eq.

② $D=0$; $\dot{x} = F(x)$ \Leftrightarrow advection & $\frac{dP}{dt} = -\partial_x (F \cdot P)$

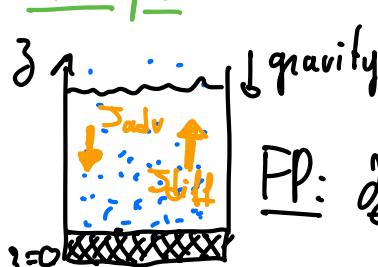
The Fokker-Planck is the combination of diffusion due to the noise & advection of probability due to the force

Conservation of probability & probability current

$\int_{-\infty}^{+\infty} P(x) dx = 1$ is a global conservation law for $P(x)$

(1) $\Leftrightarrow \frac{\partial}{\partial t} P = -\partial_x [J(x)]$ with $J(x) = +F(x)P - D\partial_x P$ is a local conservation law for the probability density and $J(x)$ is called a probability current.

Example:



$\dot{z} = -\mu \delta_{\text{avg}} + \sqrt{2\mu kT} \zeta$ when δ_{avg} is the difference between the collision map & the mass of the same volume of fluid.

$$\text{FP: } \frac{\partial}{\partial t} P = \frac{\partial}{\partial z} \left[\mu \delta_{\text{avg}} P + \mu kT \partial_z P \right] : J = \underbrace{-\mu \delta_{\text{avg}} P}_{J_{\text{adv}}} - \underbrace{\mu kT \partial_z P}_{J_{\text{diff.}}}$$

Start with $P(z,0)$ and wait until the system reaches a **steady state** in which it does not evolve statistically: $\frac{\partial}{\partial t} P(z,t) = 0 \Rightarrow \mu \delta_{\text{avg}} P + \mu kT \partial_z P = C^*$

$$\text{Since } P=0 \text{ for } z < 0, C^* = 0 \text{ & } \partial_z P = -\frac{\delta_{\text{avg}}}{kT} P \Rightarrow P(z) = P_0 e^{-\frac{\delta_{\text{avg}} z}{kT}}$$

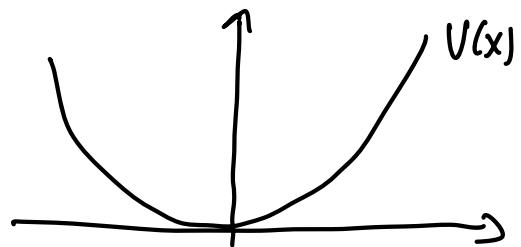
This exponential "atmosphere" is called a Peim profile & was measured experimentally by Jean Peim (Nobel prize in 1926)

More generally: $\dot{x} = -\mu V'(x) + \sqrt{2\mu T} Z(t)$, when $V(x)$ is a confining potential

(5)

The Fokker-Planck equation reads

$$\frac{\partial P}{\partial t} = \frac{\partial}{\partial x} \left[\mu h T \frac{\partial P}{\partial x} + \mu V'(x) P \right]$$



so that $P(x) = \frac{1}{Z} e^{-\frac{V(x)}{kT}}$ is a steady-state solution of the system.

This is the **Boltzmann weight** & the colloid reaches thermal equilibrium. The solvent acts like a thermostat: an equilibrated fluid drives an inert particle into an equilibrated stationary state.



Comment: For $P(x)$ to be normalizable, we need $\int dx e^{-\beta V(x)} < +\infty$
 $\Rightarrow V(x)$ has to diverge fast enough.

If $V(x) \sim \varepsilon \log|x|$, $e^{-\beta V(x)} \sim \frac{1}{|x|^{\beta \varepsilon}}$ not integrable for $\varepsilon \beta \leq 1$
 $\Rightarrow hT \geq \varepsilon$

\Rightarrow at high temperature, the system does not equilibrate.

The potentials that diverge faster than logarithmically are called **confining potentials**.